E-Content On Multiple Access Protocol

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Multiple access protocol- ALOHA, CSMA, CSMA/CA and CSMA/CD

Data Link Layer

The data link layer is used in a computer network to transmit the data between two devices or nodes. It divides the layer into parts such as **data link control** and the **multiple access resolution/protocol**. The upper layer has the responsibility to flow control and the error control in the data link layer, and hence it is termed as **logical of data link control**. Whereas the lower sub-layer is used to handle and reduce the collision or multiple access on a channel. Hence it is termed as media access control or the multiple access resolutions.

Random Access Protocol:

In this protocol, all the station has the equal priority to send the data over a channel. In random access protocol, one or more stations cannot depend on another station nor any station control another station. Depending on the channel's state (idle or busy), each station transmits the data frame. However, if more than one station sends the data over a channel, there may be a collision or data conflict. Due to the collision, the data frame packets may be lost or changed. And hence, it does not receive by the receiver end.

Following are the different methods of random-access protocols for broadcasting frames on the channel.

- Aloha
- CSMA
- CSMA/CD
- CSMA/CA

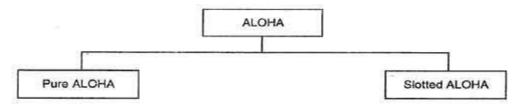
ALOHA:

ALOHA is a multiple access protocol for transmission of data via a shared network channel. It operates in the medium access control sublayer (MAC sublayer) of the open systems interconnection (OSI) model.

In the ALOHA system, a node transmits whenever data is available to send. If another node transmits at the same time, a collision occurs, and the frames that were transmitted are lost. However, a node can listen to broadcasts on the medium, even its own, and determine whether the frames were transmitted.

Aloha means "Hello". Aloha is a multiple access protocol at the data-link layer and proposes how multiple terminals access the medium without interference or collision. In 1972 Roberts developed a protocol that would increase the capacity of aloha **two fold.** The Slotted Aloha protocol involves dividing the time interval into discrete slots and each slot interval corresponds to the time period of one frame. This method requires synchronization between the sending nodes to prevent collisions.

There are two different versions of ALOHA

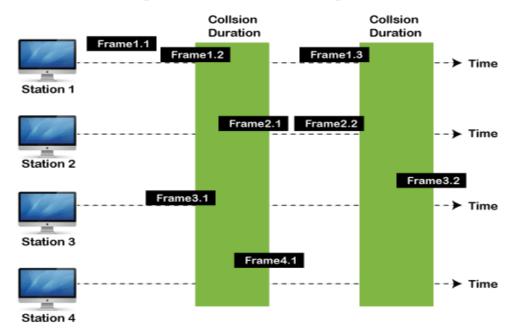


Types of ALOHA

Pure ALOHA

- In pure ALOHA, the stations transmit frames whenever they have data to send. When two or more stations transmit simultaneously, there is collision and the frames are destroyed.
- In pure ALOHA, whenever any station transmits a frame, it expects the acknowledgement from the receiver. If acknowledgement is not received within specified time, the station assumes that the frame (or acknowledgement) has been destroyed.
- If the frame is destroyed because of collision the station waits for a random amount of time and sends it again. This waiting time must be random otherwise same frames will collide again and again.
- Therefore pure ALOHA dictates that when time-out period passes, each station must wait for a random amount of time before re-sending its frame. This randomness will help avoid more collisions.

Figure shows an example of frame collisions in pure ALOHA.



Frames in Pure ALOHA

As we can see in the figure above, there are four stations for accessing a shared channel and transmitting data frames. Some frames collide because most stations send their frames at the same time. Only two frames, frame 1.1 and frame 3.2, are successfully transmitted to the receiver end. At the same time, other frames are lost or destroyed. Whenever two frames fall on a shared channel simultaneously, collisions can occur, and both will suffer damage. If the new frame's first bit enters the channel before

finishing the last bit of the second frame. Both frames are completely finished, and both stations must retransmit the data frame.

Efficiency of Pure Aloha $S = G \times e^{-2G}$

given as throughput S

$$S = Ge^{-2G}$$

G is the total number of stations transmitting at the same instant.

For maximum throughput, G must be $\frac{1}{2}$. Therefore, S = 0.184

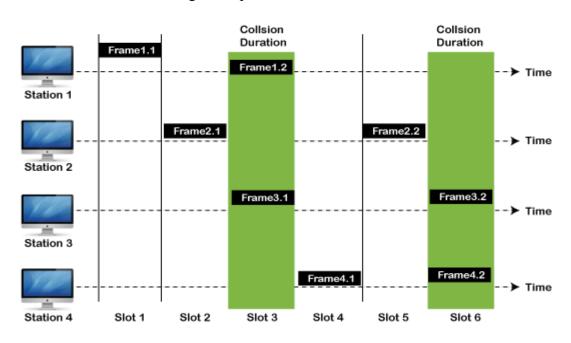
So, maximum efficiency will be 18.4%.

Slotted ALOHA

Slotted ALOHA was invented to improve the efficiency of pure ALOHA as chances of collision in pure ALOHA are very high. In slotted ALOHA, the <u>time of the shared channel is divided into discrete intervals called slots</u>. The stations can send a frame only at the beginning of the slot and only one frame is sent in each slot.

In slotted ALOHA, if any station is not able to place the frame onto the channel at the beginning of the slot *i.e.* it misses the time slot then the station has to wait until the beginning of the next time slot.

- In slotted ALOHA, there is still a possibility of collision if two stations try to send at the beginning of the same time slot as shown in fig.
- Slotted ALOHA still has an edge over pure ALOHA as chances of collision are reduced to one-half.



Frames in Slotted ALOHA

Efficiency-

Efficiency of Slotted Aloha = $G \times e^{-G}$

where G = Number of stations willing to transmit data at the beginning of the same time slot

Maximum Efficiency of Slotted Aloha = 36.8%

Difference Between Pure Aloha And Slotted Aloha-

Pure Aloha	Slotted Aloha	
Any station can transmit the data at any time.	Any station can transmit the data at the beginning of any time slot.	
The time is continuous and not globally synchronized.	The time is discrete and globally synchronized.	
Vulnerable time in which collision may occur $= 2 \ x \ T_t$	Vulnerable time in which collision may occur $= T_t$	
Probability of successful transmission of data packet $= G \times e^{-2G}$	Probability of successful transmission of data packet = G x e-G	
Maximum efficiency = 18.4% (Occurs at G = $1/2$)	Maximum efficiency = 36.8% (Occurs at G = 1)	
The main advantage of pure aloha is its simplicity in implementation.	The main advantage of slotted aloha is that it reduces the number of collisions to half and doubles the efficiency of pure aloha.	

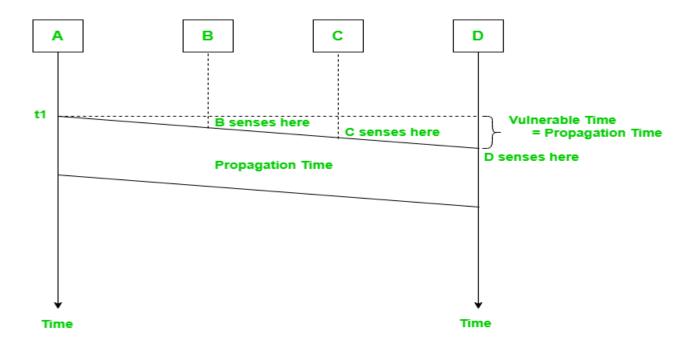
Carrier Sense Multiple Access (CSMA)

This method was developed to decrease the chances of collisions when two or more stations start sending their signals over the data link layer. Carrier Sense multiple access requires that each station **first check the state of the medium** before sending.

Vulnerable Time -

Vulnerable time = Propagation time (Tp)

It is a **carrier sense multiple access** based on media access protocol to sense the traffic on a channel (idle or busy) before transmitting the data. It means that if the channel is idle, the station can send data to the channel. Otherwise, it must wait until the channel becomes idle. Hence, it reduces the chances of a collision on a transmission medium.



CSMA Access Modes

1-Persistent: In the 1-Persistent mode of CSMA that defines each node, first sense the shared channel and if the channel is idle, it immediately sends the data. Else it must wait and **keep track** of the status of the channel to be idle and broadcast the frame unconditionally as soon as the channel is idle.

Non-Persistent: It is the access mode of CSMA that defines before transmitting the data, each node must sense the channel, and if the channel is inactive, it immediately sends the data. Otherwise, the station must wait for a random time (not continuously), and when the channel is found to be idle, it transmits the frames.

p-persistent CSMA

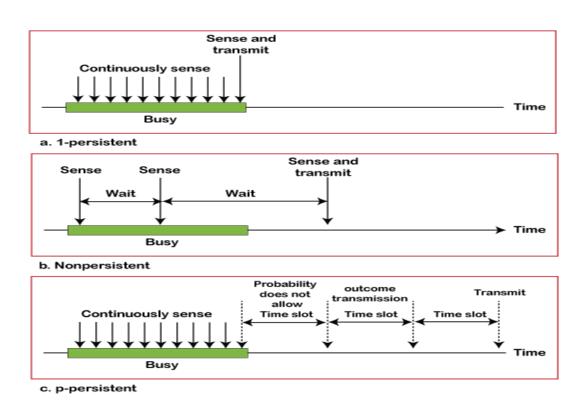
• This method is used when channel has time slots such that the time slot duration is equal to or greater than the maximum propagation delay time.

• Whenever a station becomes ready to send, it senses the channel.

If channel is busy, station waits until next slot.

If channel is idle, it transmits with a probability p.

- With the probability q=l-p, the station then waits for the beginning of the next time slot.
- If the next slot is also idle, it either transmits or waits again with probabilities p and q.
- This process is repeated till either frame has been transmitted or another station has begun transmitting.
- In case of the transmission by another station, the station acts as though a collision has occurred and it waits a random amount of time and starts again.



CSMA with Collision Detection (CSMA/CD)

Carrier Sense Multiple Access with Collision Detection (CSMA/CD) is a network protocol for carrier transmission that operates in the Medium Access Control (MAC) layer. It senses or listens whether the shared channel for transmission is busy or not, and defers transmissions until the channel is free. The collision detection technology detects collisions by sensing transmissions from other stations. On detection of a collision, the station stops transmitting, **sends a jam signal**, and then waits for a random time interval before retransmission.

Algorithms

The algorithm of CSMA/CD is:

- When a frame is ready, the transmitting station checks whether the channel is idle or busy.
- If the channel is busy, the station waits until the channel becomes idle.

- If the channel is idle, the station starts transmitting and continually monitors the channel to detect collision.
- If a collision is detected, the station starts the collision resolution algorithm.
- The station resets the retransmission counters and completes frame transmission.

The algorithm of Collision Resolution is:

- The station continues transmission of the current frame for a specified time along with a jam signal, to ensure that all the other stations detect collision.
- The station increments the retransmission counter.
- If the maximum number of retransmission attempts is reached, then the station aborts transmission.
- Otherwise, the station waits for a backoff period which is generally a function of the number of collisions and restart main algorithm.

CSMA with Collision Avoidance (CSMA/CA)

Carrier Sense Multiple Access with Collision Avoidance (CSMA/CA) is a network protocol for carrier transmission that operates in the Medium Access Control (MAC) layer. In contrast to CSMA/CD (Carrier Sense Multiple Access/Collision Detection) that deals with collisions after their occurrence, CSMA/CA prevents collisions prior to their occurrence.

Algorithm

The algorithm of CSMA/CA is:

- When a frame is ready, the transmitting station checks whether the channel is idle or busy.
- If the channel is busy, the station waits until the channel becomes idle.
- If the channel is idle, the station waits for an Inter-frame gap (IFG) amount of time and then sends the frame.
- After sending the frame, it sets a timer.
- The station then waits for acknowledgement from the receiver. If it receives the acknowledgement before expiry of timer, it marks a successful transmission.
- Otherwise, it waits for a back-off time period and restarts the algorithm.

Advantages of CMSA/CD

- CMSA/CA prevents collision.
- Due to acknowledgements, data is not lost unnecessarily.
- It avoids wasteful transmission.
- It is very much suited for wireless transmissions.

Disadvantages of CSMA/CD

•	The algorithm calls for long waiting times. It has high power consumption.	
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